



iNEMI

International Electronics Manufacturing Initiative

iNEMI Nano-Attach Project

*Grace O'Malley, iNEMI
Reporting for Project
Development Team*

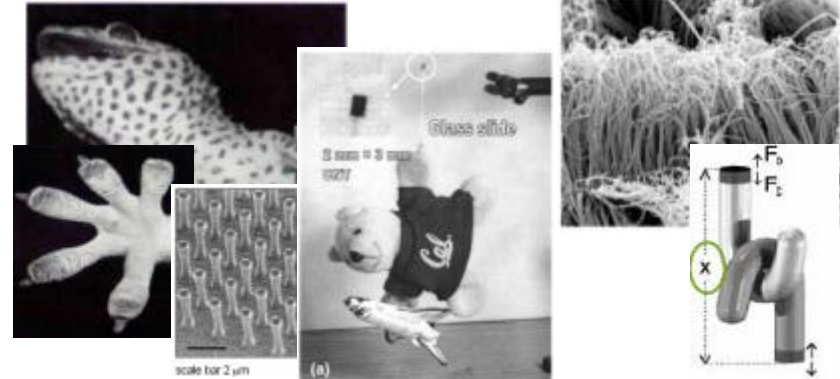
Advancing manufacturing technology

iNEMI Nano-Attach Project

Goal: Develop low-temperature or room temperature assembly processes that have the potential to improve field reliability, streamline manufacturing, and reduce cost

Strategy:

- Use nanotechnology based dry adhesive technologies, e.g., nano-velcro or biomimetic systems (“gecko foot”) to replace high temperature solder attach systems
- Project Lead: Hope Chik (Motorola)



Tactics

- **Phase 1: Discovery and Concept Development** - Define requirements necessary to adapt nano-structure attachment schemes in electronic assembly
- **Phase 2: Evaluation and Proof of Concept** - Identify and evaluate currently available nano-attach technologies and explore these approaches
- **Phase 3: Demonstration and Prototype** - Proof-of-concept material evaluation and fabrication of assembled prototypes

Milestones & Issues

- **Phase 1 – Discovery**Q407
- **Phase 2 – Evaluation**Q208
- **Phase 3 – Demonstration**Q408
- **Issues:**
 - ✓ Is the technology mature enough to have a high probability of success in Phase 2 and 3

iNEMI Nano-Attach Team Members

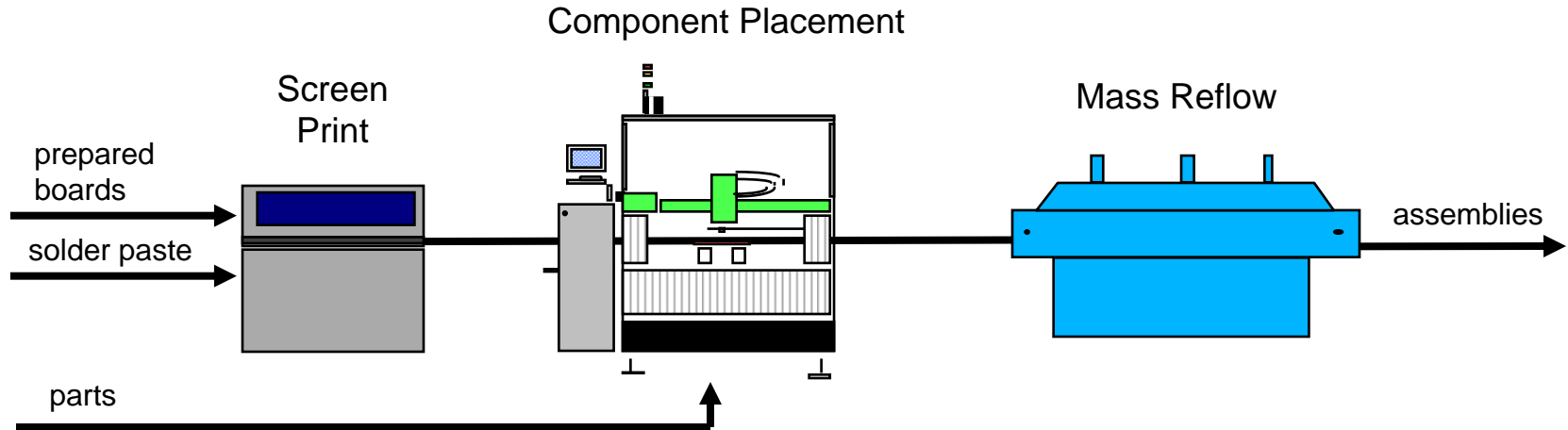


DELPHI



iNEMI

Motivation for Nano-Attach Technology



Current electronic assembly process:

- Use of elevated temperatures (mass reflow, selective soldering, conductive adhesive curing, etc.)
- Introduces thermal excursions increasing reliability risks to components and boards
- Exacerbated with even higher temperature Pb-free assembly processes
- Individualized solutions for temperature-sensitive components

Nanotechnology – The Gecko

Hierarchical structure

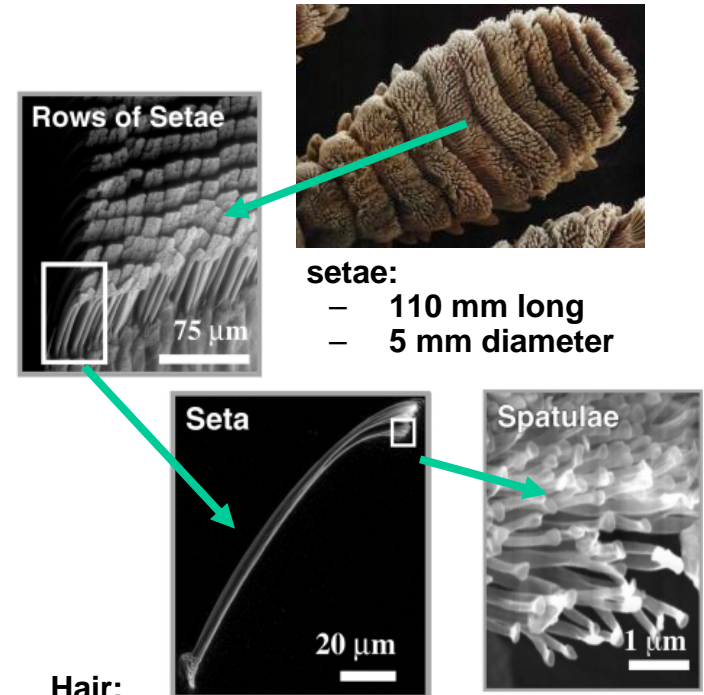


- Foot:**
- 14,400 setae/mm²
 - 10 N/cm²
 - Uses only 3% of setae

K. Autumn, "How Gecko Toes Stick", American Scientist, 94, 124 (2006)

- Unique ability to climb walls and hang from ceilings

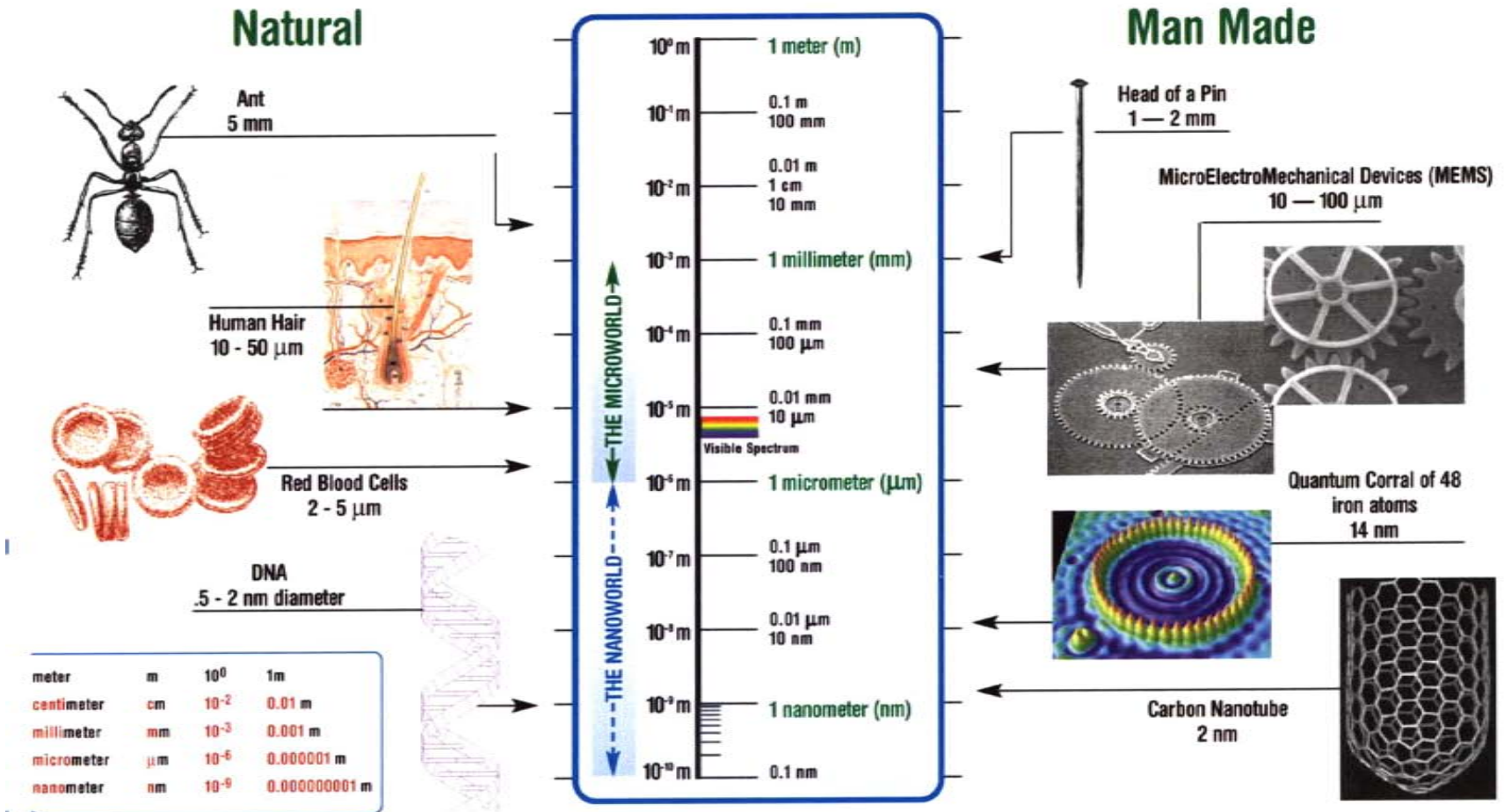
Adhesion: van der Waals forces



- Hair:**
- Branches to 100 – 1,000 hairs
 - 0.2 µm long and wide
 - Spatula-shaped endings
 - 100 nN/hair

K. Autumn, Y.A. Liang, S.T. Hsieh, W. Zesch, W.P. Chan, T.W. Kenny, R. Fearing, and R.J. Full, "Adhesive Force of a Single Gecko Foot-Hair", *Nature*, 405, 681 (2000).

What is Nanotechnology?



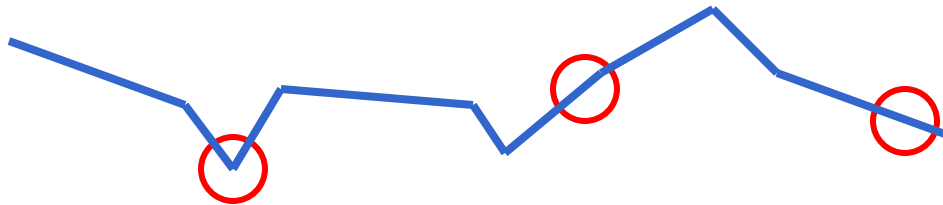
“What is Nano”, Nano 101, Forbes/Wolfe 2002

How does nanotechnology help?

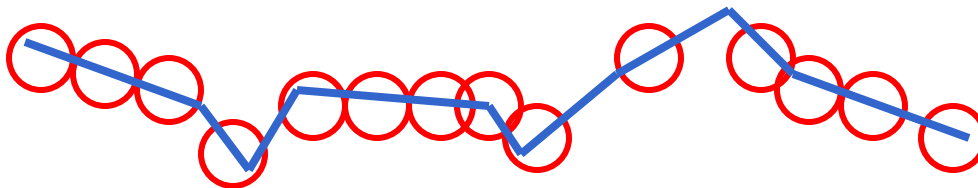
Why do two surfaces tend not to stick together?

- Surface roughness

Without nanotechnology:



With nanotechnology:



Contact Points:

1,000,000 /cm²

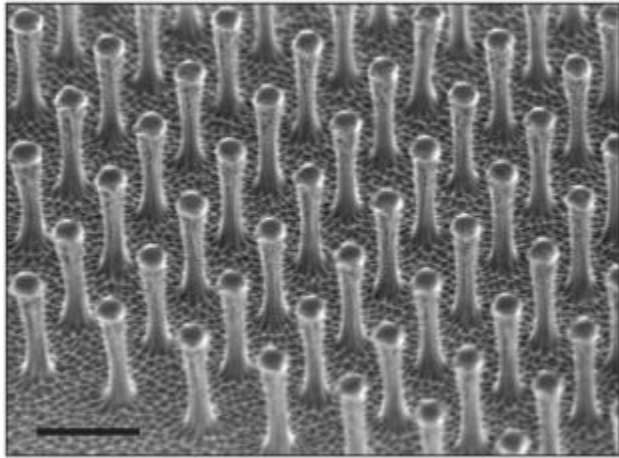
1,000,000,000 /cm²

1,000,000,000,000 /cm² ??

Synthetic Gecko: Polymer

Polyimide Hairs on Si

- e-beam lithography
- 1 cm² sample



scale bar 2 μm

Proof-of-concept Experiments:

Control:

$<0.001 \text{ N/cm}^2$

Nanostructures on Silicon:

0.01 N/cm^2

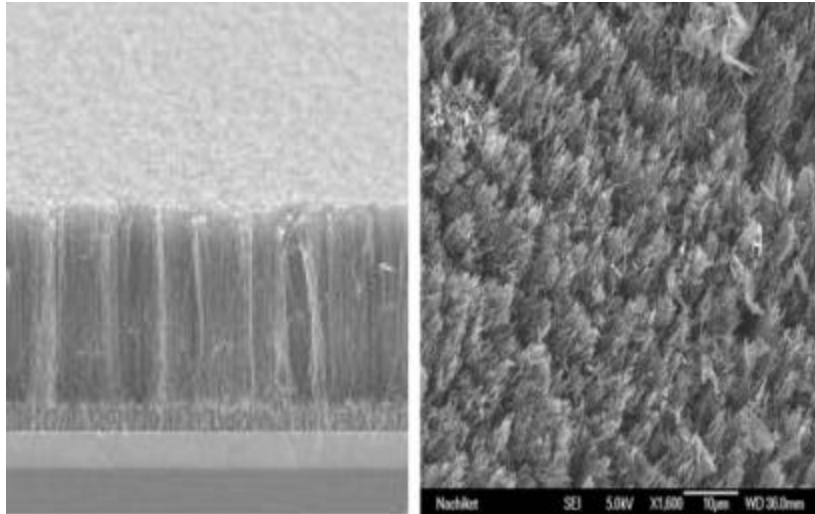
Nanostructures with flexible substrate:

3 N/cm^2

need for conformal contact

A.K. Geim, S.V. Dubonos, I.V. Grigorieva, K.S. Novoselov, A.A. Zhukov, and S.Yu. Shapoval, "Microfabricated Adhesive Mimicking Gecko Foot-Hair", *Nature Mat.*, 2, 461 (2003).

Synthetic Gecko: Carbon Nanotube



side view

top view

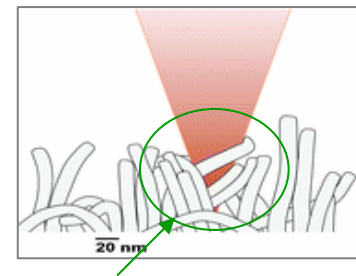
Does it scale to larger surfaces?

Vertical probe

- Density $7E11 / \text{cm}^2$
- $1.6 \times 10^{-2} \text{ nN/nm}^2$ [$1,600 \text{ N/cm}^2$]

Control

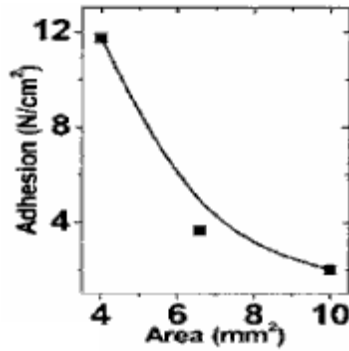
- Negligible adhesion without CNTs



small, highly efficient contact area

B. Yurdumakan, N.R. Raravikar, P.M. Ajayan, and A. Dhinojwala, "Synthetic Gecko Foot-Hairs from Multiwalled Carbon Nanotubes", *Chem. Commun.*, 3799 (2005).

Synthetic Gecko: Carbon Nanotube



Adhesion to Glass Slide

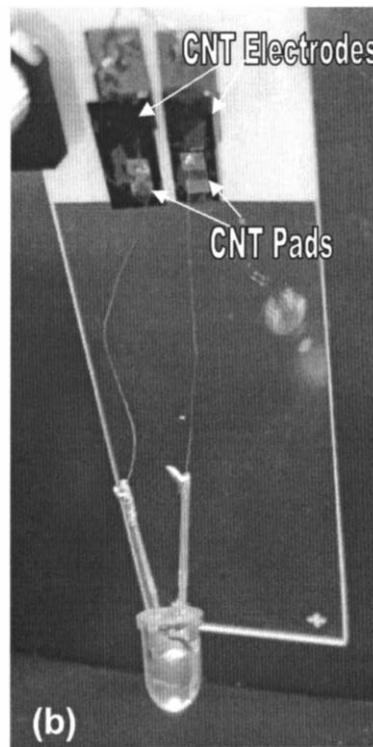
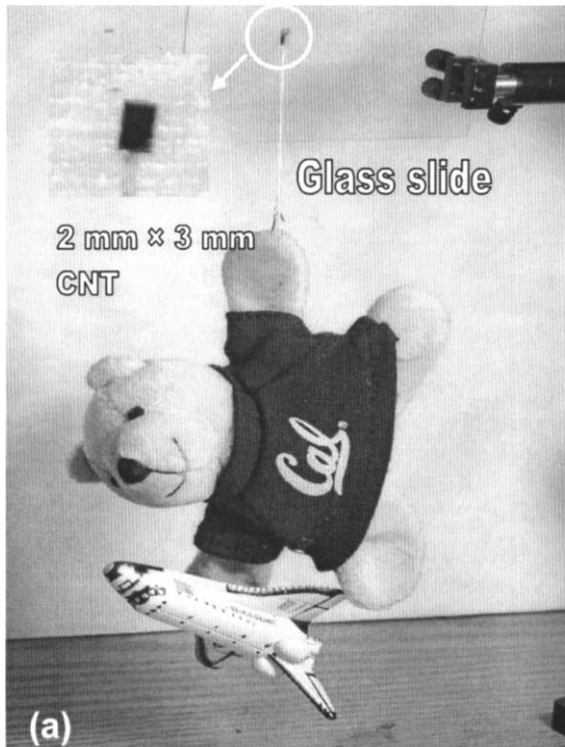
- **11.7 N/cm²** with 4 mm² contact area
- Decreases with larger sample size
- Negligible adhesion at 20 mm² contact area
- Surface roughness?

Y. Zhao, T. Tong, L. Delzeit, A. Kashani, M. Meyyappan, and A. Majumdar, "Interfacial Energy and Strength of Multiwalled-Carbon-Nanotube-Based Dry Adhesive", *J. Vac. Sci. Technol. B*, 24, 1071 (2006).

Carbon Nanotube Properties

	Current Performance	Current Material Systems	Carbon Nanotubes
Tensile Strength	~2 GPa	High-strength steel alloys	~45 GPa
Current Carrying Capacity	~1E6 A/cm ²	Copper wires	1E9 A/cm ² (estimated)
Thermal	3,320 W/m*K	Diamond	6,000 W/m*K (predicted)

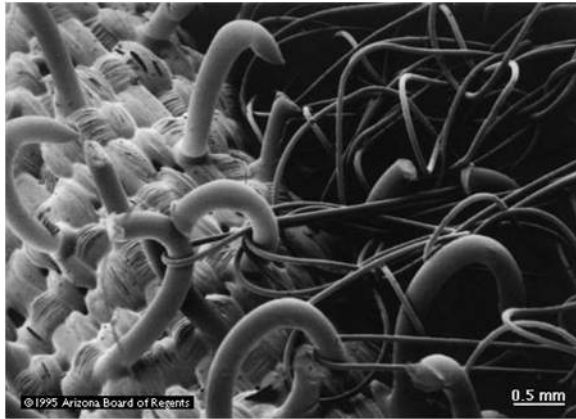
Synthetic Gecko Demonstrations



Y. Zhao, T. Tong, L. Delzeit, A. Kashani, M. Meyyappan, and A. Majumdar, "Interfacial Energy and Strength of Multiwalled-Carbon-Nanotube-Based Dry Adhesive", *J. Vac. Sci. Technol. B*, 24, 1071 (2006).

A.K. Geim, S.V. Dubonos, I.V. Grigorieva, K.S. Novoselov, A.A. Zhukov, and S.Yu. Shapoval, "Microfabricated Adhesive Mimicking Gecko Foot-Hair", *Nature Mat.*, 2, 461 (2003).

Nanotechnology - Nano-Velcro

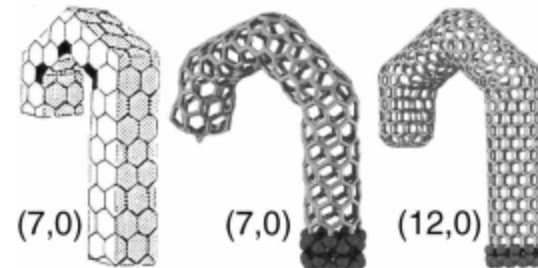


Velcro:

- Two-sided attachment scheme as need for nanostructures on both surfaces
- Hook & loop
- 2 hooks

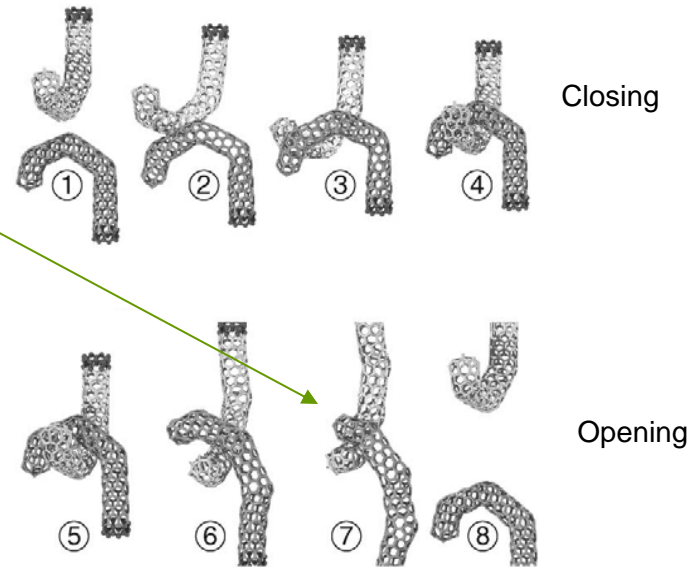
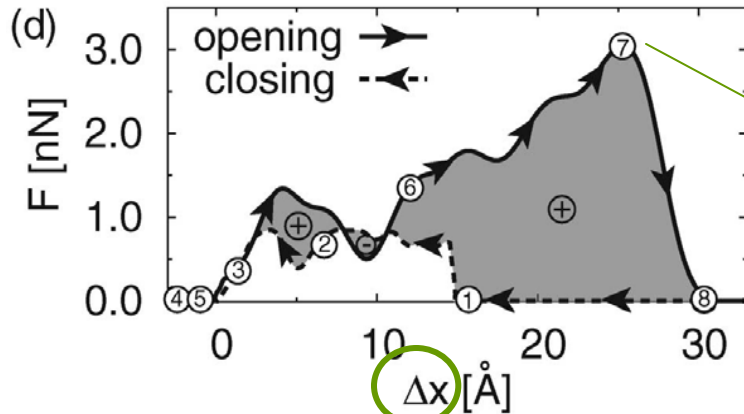
Carbon Nanotube Hooks

- Substitution of hexagon structure with heptagon-pentagon structures
- Energetically unfavorable
- System is flexible enough to redistribute strain



S. Berber, Y-K. Kwon, and D. Tomanek, "Bonding and Energy Dissipation in a Nanohook Assembly", *Phys. Rev. Lett.*, 91, 165503 (2003).

Nano-Velcro (Nano-Hooks)



Modeling:

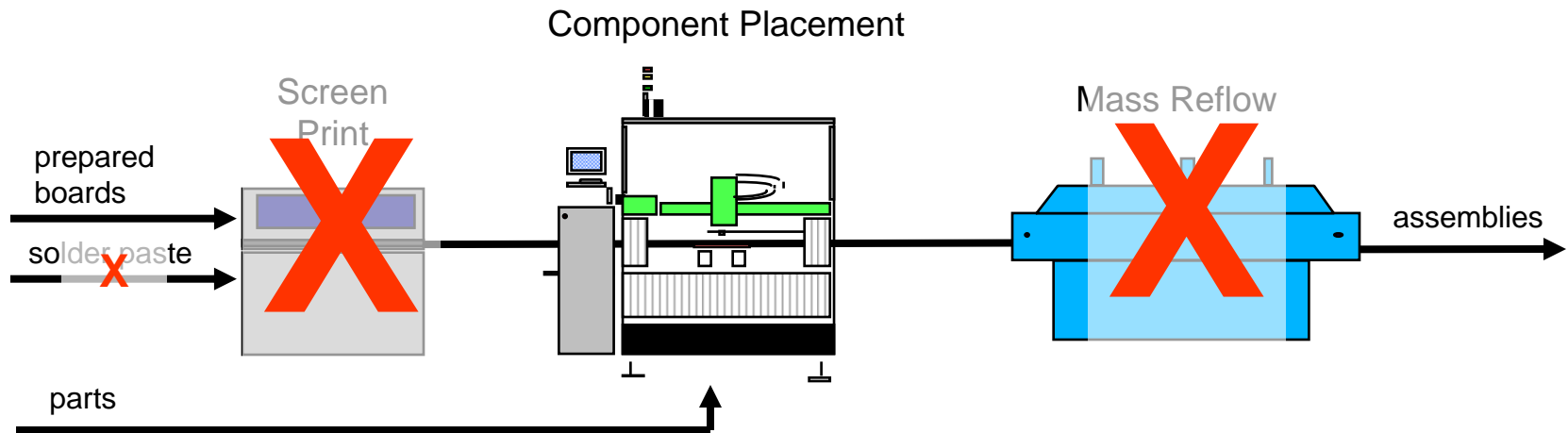
- Peak closing force 0.9 nN
- Peak opening force 3.0 nN
- 1 hook/nm² [density 10¹⁴/cm²]
- 300,000 N/cm²

Adhesion Reference:

Tape ~1s N/cm², Solder ~1,000s N/cm²

S. Berber, Y-K. Kwon, and D. Tomanek, "Bonding and Energy Dissipation in a Nanohook Assembly", *Phys. Rev. Lett.*, 91, 165503 (2003).

Example of Nano-Attach Assembly Process



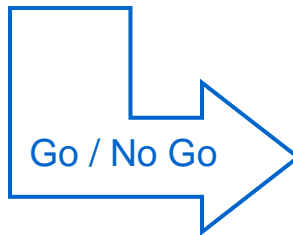
Potential benefits with nanotechnology approach:

- Room temperature process
- Streamline manufacturing
- Improve field reliability
- Simplified rework
- Reduce cost

Nano-Attach Project Goals

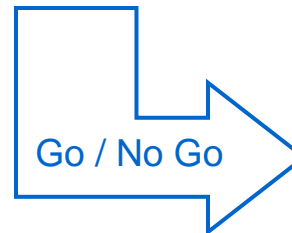
Phase 1: Discovery and Concept Development

- Define **application** requirements
- Benchmarking nano-attach **technology**
- Cost effective implementation



Phase 2: Evaluation and Proof-of-Concept

- Material study
- Design guidelines
- Assembly development



Phase 3: Demonstration and Prototype

- Build working prototype
- Develop supply chain

Phase 1: Discovery and Concept Development

Deliverables:

- Publish design targets for industrial development
- Publish design targets derived from Phase 1 findings
 - Generate interest in the electronics industry
 - Attract new players
 - Accelerate development
- Refine project plan, deliverables, and timeline for Phase 2
- Publish white paper summary for iNEMI members
- Recommend go/no-go for Phase 2

Issue: Is the material technology mature enough to have a high probability of success in Phase 2?

Gate 1: Go / No Go



Phase 2: Evaluation and Proof-of-Concept

Deliverables:

- Define and develop evaluation vehicle(s)
- Define materials characterization methods
- Performance assessment using evaluation vehicle(s)
 - Assembly
 - Reliability
- Develop material design guidelines
- Publish summary of test results
- Refine project plan and timeline for Phase 3
- Publish white paper summary for iNEMI members
- Recommend go/no-go for Phase 3

Issue: Is the technology mature enough to have a high probability of success in Phase 3?

Gate 2: Go / No Go



Phase 3: Demonstration and Prototype

Deliverables:

- Demonstrate prototype device
- Present prototype vehicle test results
- Supply chain identified
- Publish white paper summary for iNEMI members
- Recommend next steps

Nano-Attach Project: Current Status

- **Compiled list of applications that would benefit from nano-attachment technology and their (mechanical, electrical, thermal) requirements**
 - Identified electronic and non-electronic assembly applications
- **Identify technology gaps**
 - Preparations for Phase 2 work
- **Discussions with technology leaders**
 - Potential collaboration / partnership

Summary

Potential Low-Temperature Assembly

Technology at Research / Proof-of-Concept Stage

Lots of Questions (i.e. performance, reliability)

Exciting Opportunities



Paradigm Shift in Assembly



www.inemi.org

Email contact:

Hope Chik

Email address

hope.chik@motorola.com



INEMI

Advancing manufacturing technology